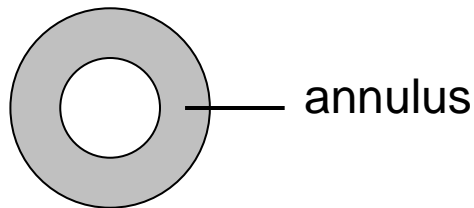


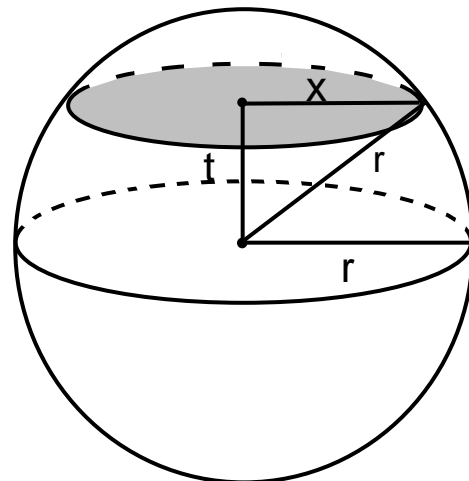
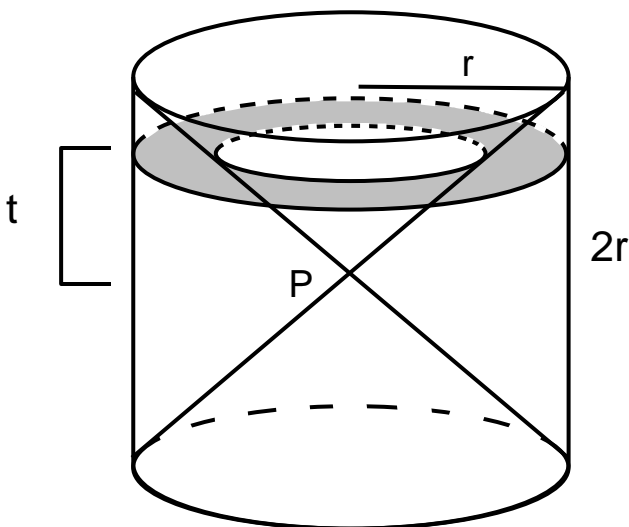
Definitions:

Concentric circles are circles that have the same center but radii of different lengths.

The region bound by concentric circles is called the annulus.



Volume of a Sphere:

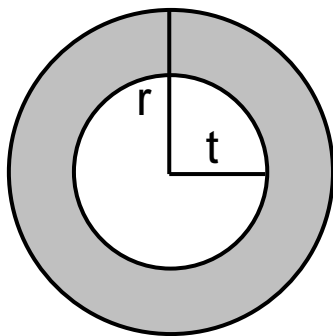


Slice both figures with a parallel plane t units above the centers.

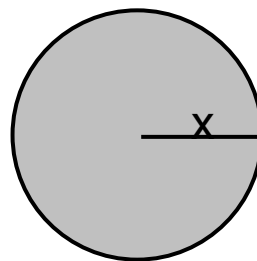
Note the right triangle formed in the sphere with sides t , r , and x . Using Pythagorean Theorem we get:

$$x^2 = r^2 - t^2$$

Cross sections of both figures:



$$\begin{aligned} \text{Area} &= A_{lg} - A_{sm} \\ \text{Area} &= \pi r^2 - \pi t^2 \end{aligned}$$



$$\begin{aligned} \text{Area} &= \pi x^2 \\ \text{Area} &= \pi (r^2 - t^2) \text{ (substitute } x^2 \text{ above)} \\ \text{Area} &= \pi r^2 - \pi t^2 \end{aligned}$$

Same!!

***By Cavalieri's Principle, since every horizontal plane cuts the figures into regions with equal areas, the volume of the sphere equals the volume of the solid between the cones and the cylinder.

$$\begin{aligned}
V_{\text{sphere}} &= V_{\text{cylinder}} - V_{2\text{cones}} \\
V &= \pi r^2 H - 2\left(\frac{1}{3}\pi r^2 H\right) \\
V &= \pi r^2(2r) - 2\left(\frac{1}{3}\pi r^2(r)\right) \\
V &= 2\pi r^3 - \left(\frac{2}{3}\right)\pi r^3 \\
V &= \left(\frac{4}{3}\right)\pi r^3
\end{aligned}$$

Theorem 11.7: The volume of a sphere is $\frac{4}{3}\pi$ times the cube of the radius: $V = \frac{4\pi r^3}{3}$

Example: Find the volume of a sphere of radius 3.

$$\begin{aligned}
V &= \left(\frac{4}{3}\right)\pi(3^3) \\
V &= \left(\frac{4}{3}\right)\pi(27) \\
V &= 36\pi \text{ cubic units}
\end{aligned}$$

Sample Problem: Find the volume of a sphere whose great circle has a circumference of 16π .

$$\begin{array}{ll}
C = 2\pi r & V = \left(\frac{4}{3}\right)\pi(8^3) \\
16\pi = 2\pi r & V = \left(\frac{4}{3}\right)\pi(512) \\
r = 8 & V = \left(\frac{2048\pi}{3}\right)
\end{array}$$

Regular Polygon	Volume
tetrahedron	$V = \frac{\sqrt{2}}{12} e^3$
cube (hexahedron)	$V = e^3$
octahedron	$V = \frac{\sqrt{2}}{3} e^3$
dodecahedron	$V = \left(\frac{15 + 7\sqrt{5}}{3} \right) e^3$
icosahedron	$V = \left(\frac{15 + 5\sqrt{5}}{12} \right) e^3$

Construction 16: Segment division

Given: \overline{AB}

Construct: Five congruent segments with lengths that total \overline{AB} .

1. Draw a ray from A, forming an acute angle.
2. Place the point of the compass at A and, without changing the compass measure, mark off five equal segments on the ray. Label the points F, G, H, I, and J.
3. Draw \overline{BJ} .
4. Draw lines parallel to \overleftrightarrow{BJ} through F, G, H, and I. You can do this by constructing congruent corresponding angles at each point. Copy $\angle AJB$ at vertices F, G, H, and I.

These parallel lines cut \overline{AB} into five equal segments.

Construction 17: Regular Hexagon

1. Draw a circle.
2. Using the radius of the circle, mark off six consecutive arcs.
3. Connect the arc intersections with segments to form a regular hexagon.

3 Impossible Constructions:

1. Squaring a Circle: Given a circle, construct a square with the same area.
2. Doubling a Cube: Given a cube, construct a cube whose volume is twice the volume of the original cube.
3. Trisecting an Angle

Chapter 11 Vocabulary:

- annulus
- Cavalieri's principle
- concentric circles
- Congruent Solids Postulate
- cross section
- cubic unit
- oblique prism
- section
- volume
- Volume Addition Postulate
- Volume of a Cube Postulate
- Volume Postulate

Notes on test:

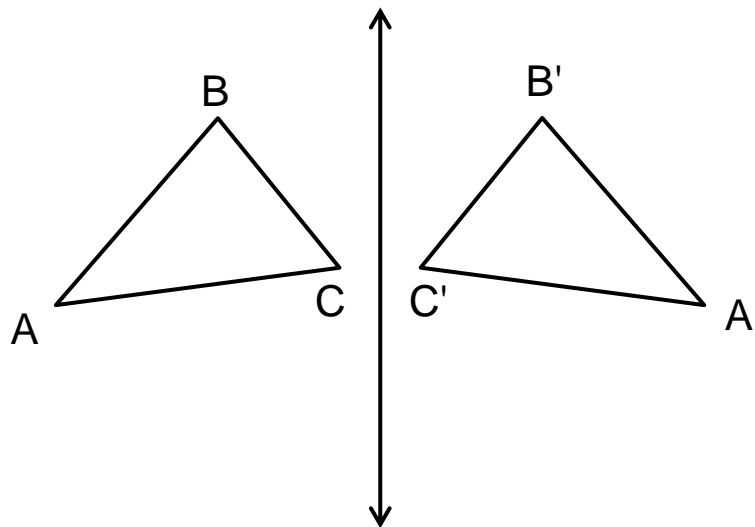
- Match formulas with figures
- Given figures, find volumes
- Short answer questions on Congruent Solids Postulate, volume definition, Cavalieri's Principle, and parallelepipeds
- Word Problems
- No Proofs

The word transformation describes a change in appearance of points in a plane. The geometric figure before a transformation is called the preimage. The resulting figure after the transformation is called the image.

Definition:

A transformation is a one-to-one function from the plane onto the plane.

Reflections



Reflection in a line is when the line acts as a mirror.

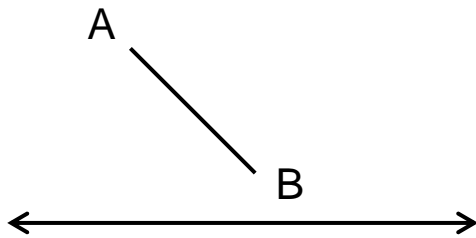
Definition:

A reflection in a line, n , is a transformation that maps each point A of a plane onto the point A' such that the following conditions are met:

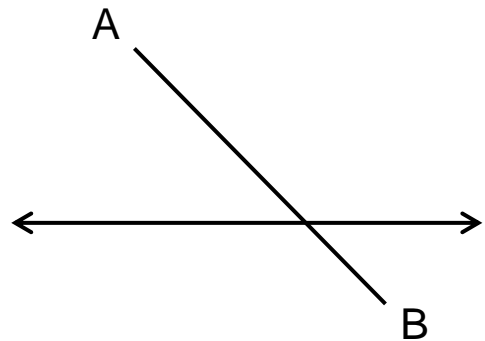
1. If A is on n , then $A = A'$.
2. If A is not on n , then n is the perpendicular bisector of $\overline{AA'}$.

Sample Problems: Find the image of reflection.

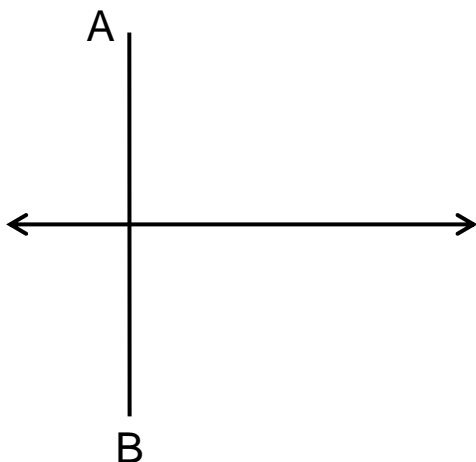
1.



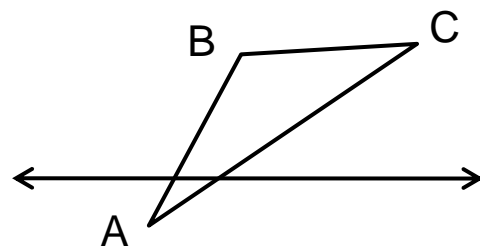
2.



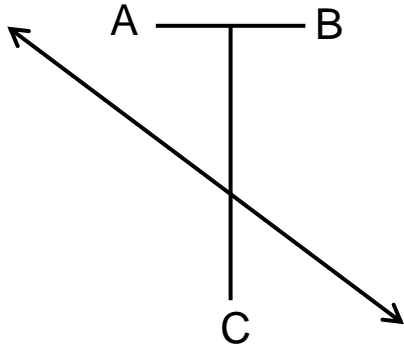
3.



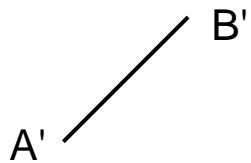
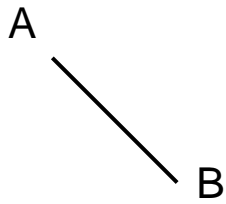
4.



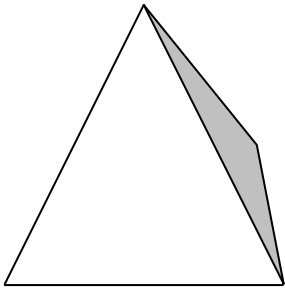
5.



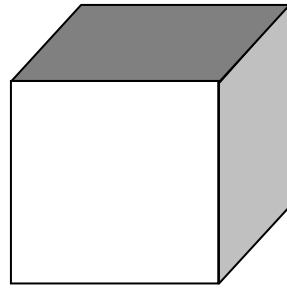
Sample Problem: Draw the line of reflection.



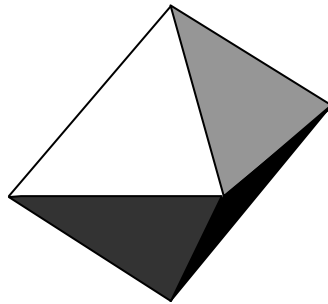
Platonic Solids



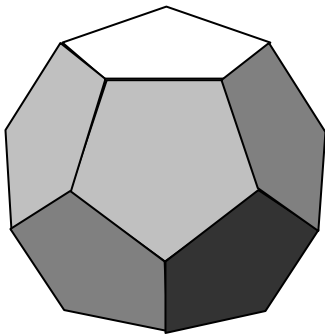
Tetrahedron



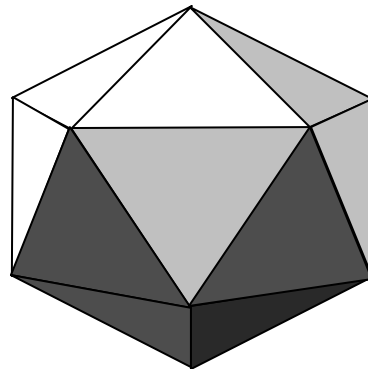
Hexahedron
(cube)



Octahedron



Dodecahedron



Icosahedron